The Hydra[®] Magnum represents the backbone of Oceaneering's fleet of high-powered remotely operated vehicle (ROV) work systems with deepwater capabilities. Reliable and easily maintained, the ROV provides a 170 hp, high-thrust, cage-deployed system that is designed to accommodate underwater intervention tasks in support of oil and gas drilling, construction, and production activities.

The Hydra[®] Magnum evolved from years of experience in deepwater work class ROV operations.

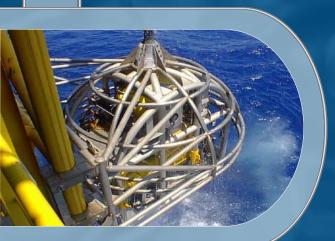
The ROV delivers performance in water depths to 10,000 fsw and also in severe weather conditions.

Oceaneering maintains a world leadership position in providing deepwater work class ROVs to the oil and gas industry. The Hydra[®] Magnum ROV is one several types of ROVs in the company's extensive fleet that are designed and built at Oceaneering's Morgan City, Louisiana facility.

Fiber optics are used as the primary transmission link for all video and data signals between the vehicle and the surface control console. This allows extremely high quality video technology as well as plug and play installation of sensors and equipment.



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The side-entry cage, with a capacity of 1,600 ft of neutrally buoyant flying tether, provides protection during launch and recovery, makes deployment and recovery more efficient in marginal weather and high currents, provides additional tooling capabilities and storage, and provides additional payload for the deployment and recovery of subsea equipment.





Vehicle

| Verneie | |
|----------------|----------------------------|
| Length: | 8.5 ft |
| Width: | 4.8 ft |
| Height: | 6 ft |
| Weight in air: | 5,600 lbs |
| Frame: | 6061 T6 Aluminum |
| Fittings: | 316 Stainless Steel |
| Depth Rating: | 10,000 ft |
| Payload: | 500 lbs |
| Horsepower: | 2 ea 85 hp Hydraulic Power |
| | Units (170 hp) |
| Propulsion: | 4 x Vectured Horizontal |
| | 2 x Vertical |
| Thrust: | |

Thrust:

| Forward/Reverse: | 1,600 lbs |
|---------------------|-----------------------------------|
| Lateral: | 1,600 lbs |
| Vertical: | 1,000 lbs |
| Power Requirements: | 480 VAC, 3 phase, 60 Hz |
| Telemetry/Control: | Asynchronous serial data |
| | transmission microprocessor |
| | control for auto heading, depth, |
| | altitude, & cruise, data displays |
| Lighting: | 8 x 250 watts |
| Cameras: | 1 x Wide angle Low Light |
| | 1 x Color CCD |
| | 2 x B&W CCD tooling |
| | 1 x B&W CCD aft |

Navigation:

- Mesotech MS900 color imaging sonar
- ٠ Honeywell HMR3000 gyrocompass
- Dinsmore directional heading sensor •
- Paroscientific Digiquartz depth sensor • Manipulators:
- 1 x 7 function Schilling Conan
- 1 x 7 function Schilling Orion
- (Spatially Corespondent Optional) •

Umbilical

High-strength, armored opto-electro-mechanical 10,000 ft

Subsea Deployment Cage

| | • |
|------------------|-------------------|
| Length: | 11 ft |
| Width: | 6.6 ft |
| Height: | 12 ft |
| Weight in air: | 7,400 lbs |
| Weight in water: | 4,050 lbs |
| HPU: | 50 hp |
| Tether: | 1,000 ft Standard |
| | 1,600 ft Optional |
| Camera: | 1 x B&W CCD |
| Lighting: | 2 x 250 watts |
| | |

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Deployment System

| Dynacon 421/42 | 1D3 Winch |
|------------------|---------------------|
| Length: | 14 ft 10 in |
| Width: | 10 ft 8 in |
| Weight (w/cable) | : 48,000 lbs |
| Dynacon 6021 D | ocking Head A-frame |
| Length: | 38 ft |
| Width: | 11.5 ft |
| Weight: | 65,000 lbs |
| - | |

Standard Tooling Packages

- 1.25 in Dia. wire rope cutter
- 1 in fiber rope cutter
- Ring gasket replacement tool
- TP03 dredge/jet pump, Rotary grinder/cutter/buffer

Control / Work Vans

| Lengths: | 14 / 16 ft | |
|---|--------------------|--|
| Width: | 8 ft | |
| Height: | 8 ft | |
| Weights: | 9,960 / 14,000 lbs | |
| Constructed of Aluminum | | |
| Options include stacking and Positive Pressure vans | | |